# Sample Final C, Math 1554

# PLEASE PRINT YOUR NAME CLEARLY IN ALL CAPITAL LETTERS

First Name \_\_\_\_\_ Last Name \_\_\_\_\_

GTID Number:

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Section Number (e.g. A4, QH3, etc.) \_\_\_\_\_ TA Name \_\_\_\_\_

## **Student Instructions**

- Show your work and justify your answers for all questions unless stated otherwise.
- Organize your work in a reasonably neat and coherent way.
- Calculators, notes, cell phones, books are not allowed.
- Use dark and clear writing: your exam will be scanned into a digital system.
- Exam pages are double sided. Be sure to complete both sides.
- Leave a 1 inch border around the edges of exams.
- Any work done on scratch paper will not be collected and will not be graded.

You do not need to justify your reasoning for questions on this page.

- 1. (6 points) Circle **true** if the statement is true, otherwise, circle **false**.
  - (a) A product of invertible matrices is also invertible.

#### true false

(b) Regardless what A and  $\vec{b}$  are, there is always at least one least-squares solution  $\hat{x}$  to  $A\vec{x} = \vec{b}$ . Assume A is mxn and b is in R^m so that Ax=b is defined.

#### true false

(c) If  $A\vec{x}_0 = \vec{b}$ , and  $A\vec{y} = \vec{0}$ , then  $\vec{x} = \vec{x}_0 - 5\vec{y}$  is a solution to  $A\vec{x} = \vec{b}$ .

## true false

(d) An example of a quadratic form is the polynomial  $7x_1^2 + 5x_2^2 - 10x_1x_2 + x_2$ .

#### true false

(e) If a matrix is invertible then it is also diagonalizable.

#### true false

(f) A  $n \times n$  matrix A and its echelon form E have the same eigenvalues.

#### true false

- 2. (6 points) Circle **possible** if the set of conditions are create a situation that is possible, otherwise, circle **impossible**.
  - (a) The columns of matrix A are linearly independent, and  $NullA^T$  is not trivial.

#### possible impossible

(b) A is  $n \times n$ ,  $\lambda \in \mathbb{R}$  is an eigenvalue of A, and dim $(\operatorname{Col}(A - \lambda I)^{\perp}) = 0$ .

#### possible impossible

(c) Stochastic matrix P has zero entries and is regular.

#### possible impossible

(d) A is a square matrix that is not diagonalizable, but  $A^2$  is diagonalizable.

#### possible impossible

(e) A is  $5 \times 4$ ,  $A\vec{x} = \vec{b}$  has three free variables, and dim $(\text{Row}(A)^{\perp}) = 3$ .

#### possible impossible

(f) A  $m \times n$  matrix A has linear transformation  $T_A$ . The map  $T_A$  can be one-to-one but not onto.

possible impossible

#### You do not need to explain your reasoning for questions on this page.

- 3. (8 points) If possible, give an example of the following. If it is not possible, write "not possible".
  - (a) A matrix that is  $2 \times 4$ , in reduced echelon form, with the dimension of column space being 3, and dimension of null space is 1.
  - (b) A  $3 \times 4$  matrix with orthonormal columns.
  - (c) A 3 × 2 matrix A in reduced echelon form so that  $A^T A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ .

(d) A stochastic matrix for the Markov Chain below.



(e) A 2 × 2 matrix whose column space is the line  $2x_1 + x_2 = 0$ , and whose null space is the line  $4x_1 - x_2 = 0$ .

4. (10 points) A has exactly two distinct eigenvalues, which are -2, and 1.

$$A = \begin{pmatrix} 0 & 1 & -1 \\ 1 & 0 & 1 \\ -1 & 1 & 0 \end{pmatrix}$$

(a) Construct an eigenbasis for eigenvalue  $\lambda = -2$ .

(b) Construct an eigenbasis for eigenvalue  $\lambda = 1$ .

(c) If possible, construct matrices P and D such that  $A = PDP^T$ , and P is a matrix with orthonormal columns and D is a diagonal matrix.

5. (10 points) Construct the singular value decomposition of  $A = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix}$ .

- 6. (6 points) Circle **true** if the statement is true, otherwise, circle **false**. You do not need to explain your reasoning.
  - (a) For any  $n \times n$  matrix A, and non-zero vectors x and y with Ax = 2x and Ay = 3y, then x and y are orthogonal.

#### true false

(b) A  $n \times n$  matrix A and  $A^T$  have the same eigenvectors.

#### true false

(c) For two matrices A, B, if the product AB is defined, then  $(AB)^T = A^T B^T$ .

true

# true false

(d) If  $\vec{x}, \vec{y} \in \mathbb{R}^n$ , then the span of  $\{\vec{x}, \vec{y}\}$  is equal to the span of  $\{\vec{x}, \vec{x} - \vec{y}\}$ .

#### true false

(e) This is a subspace of  $\mathbb{R}^3$ :  $H = \{\vec{x} \in \mathbb{R}^3 : x_1 - x_2 + x_3 = 1\}$ 

#### false

(f) For any matrix A, if  $x \in \text{Col}A$ , and  $y \in \text{Null}A$ , then  $x^T y = 0$ .

#### true false

- 7. (4 points) Circle **possible** if the set of conditions are create a situation that is possible, otherwise, circle **impossible**. You don't need to explain your reasoning.
  - (a) Matrix A is  $5 \times 10$ ,  $b \in \mathbb{R}^5$ , and Ax = b has a unique solution.

#### possible impossible

(b) Matrix A has echelon form E, and Null $A \neq$  NullE.

#### possible impossible

(c) Matrix A has a null space of dimension 1, and the linear transformation  $T_A$  is one to one.

#### possible impossible

(d) Matrix A is  $3 \times 4$  and has orthonormal columns.

possible impossible

You do not need to explain your reasoning for questions on this page.

- 8. (4 points)  $H = \{ \vec{x} \in \mathbb{R}^4 : x_1 = 5x_4 \}.$ 
  - (a) Write down a basis for H.

(b) Write down a basis for  $H^{\perp}$ .

- 9. (4 points) Fill in the blanks.
  - (a) Complete the matrix below so that the least squares solution to Ax = b does not have a unique solution

$$\begin{pmatrix} 1 & & \\ 1 & & \\ 1 & & \\ 1 & & \\ \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 4 \\ 0 \\ 1 \end{pmatrix}$$

(b) For the system below, give an example of a choice of vector  $\vec{b}$  for which the system is inconsistent.

$$\begin{pmatrix} 2 & 3\\ 0 & 0\\ 4 & 6 \end{pmatrix} \vec{x} = \vec{b} = \begin{pmatrix} ----\\ ---- \end{pmatrix}$$

(c) The dimension of the subspace of  $\mathbb{R}^4$  spanned by the vectors below is \_\_\_\_\_.

$$\begin{pmatrix} 1\\2\\3\\4 \end{pmatrix}, \quad \begin{pmatrix} 1\\0\\0\\4 \end{pmatrix}, \quad \begin{pmatrix} 0\\-2\\-3\\0 \end{pmatrix}$$

(d) If  $A = \begin{pmatrix} \vec{a_1} & \vec{a_2} \end{pmatrix}$  has QR factorization  $QR = \begin{pmatrix} \vec{q_1} & \vec{q_2} \end{pmatrix} \begin{pmatrix} 2 & 4 \\ 0 & 3 \end{pmatrix}$ , the length of  $\vec{a_2}$  is \_\_\_\_\_.

Math 1554, Sample Final C. Your initials: \_\_\_\_\_ You do not need to justify your reasoning for questions on this page.

10. (4 points) Below is a SVD factorization for a matrix  $A = U\Sigma V^T$ , where

$$U = \begin{bmatrix} \vec{u}_1 & \vec{u}_2 & \vec{u}_3 \end{bmatrix}, \ \Sigma = \begin{bmatrix} 5 & 0 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 \end{bmatrix}, \ V = \begin{bmatrix} \vec{v}_1 & \vec{v}_2 & \vec{v}_3 & \vec{v}_4 & \vec{v}_5 \end{bmatrix}$$

Fill in the blanks.

- (a) What is the rank of A?
- (b) What is the largest value of  $||A\vec{x}||$ , subject to  $||\vec{x}|| = 1$ ?
- (c) List an orthonormal basis for NullA.
- (d) List an orthonormal basis for ColA.
- 11. (6 points) If possible, give an example of the following. If it is not possible, write "not possible".
  - (a) A matrix, A, that is in echelon form, and

dim 
$$((\operatorname{Row}(A))^{\perp}) = 3,$$
 dim  $((\operatorname{Col}(A))^{\perp}) = 1$ 

(b) A  $2 \times 2$  matrix in RREF, is diagonalizable, and is singular.

(c) A 2 × 3 matrix, A, in RREF, and Null(A) is spanned by  $\vec{v} = \begin{pmatrix} -3 \\ 4 \\ 1 \end{pmatrix}$ .

12. (4 points) Calculate the least squares solution,  $\hat{x}$ , to the equation below. Don't forget to show your work.

13. (2 points) What is the symmetric matrix A associated to the quadratic form below.

$$x_1^2 - 9x_2^2 - x_3^2 + 16x_1x_3$$

14. (2 points) S is the parallelogram determined by  $\vec{v}_1 = \begin{pmatrix} 2 \\ -2 \end{pmatrix}$ , and  $\vec{v}_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ . If  $A = \begin{pmatrix} 1 & 3 \\ 4 & 2 \end{pmatrix}$ , what is the area of the image of S under the map  $\vec{x} \mapsto A\vec{x}$ ? Justify your reasoning.

15. (4 points) For what values of  $\vec{b} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$  is the system below consistent? Express your answer using parametric vector form. Justify your reasoning.

$$\begin{pmatrix} 0 & 4 \\ 1 & 3 \\ 2 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$$

16. (5 points) Consider the sequence of row operations that reduce matrix A to the identity.

$$A = \underbrace{\begin{pmatrix} -1 & 2 & 0\\ 1 & 0 & 0\\ 0 & 4 & 1 \end{pmatrix}}_{A} \sim \underbrace{\begin{pmatrix} 1 & 0 & 0\\ -1 & 2 & 0\\ 0 & 4 & 1 \end{pmatrix}}_{E_{1}A} \sim \underbrace{\begin{pmatrix} 1 & 0 & 0\\ 0 & 2 & 0\\ 0 & 4 & 1 \end{pmatrix}}_{E_{2}E_{1}A} \sim \underbrace{\begin{pmatrix} 1 & 0 & 0\\ 0 & 2 & 0\\ 0 & 0 & 1 \end{pmatrix}}_{E_{3}E_{2}E_{1}A} \sim \underbrace{\begin{pmatrix} 1 & 0 & 0\\ 0 & 1 & 0\\ 0 & 0 & 1 \end{pmatrix}}_{E_{4}E_{3}E_{2}E_{1}A} = I_{3}$$

(i) Construct the four elementary matrices  $E_1$ ,  $E_2$ ,  $E_3$ , and  $E_4$ .

- (ii) Consider the matrix products listed below. Which (if any) represents A, and which (if any) represents  $A^{-1}$ ?
  - (a)  $E_1^{-1}E_2^{-1}E_3^{-1}E_4^{-1}$
  - (b)  $E_4 E_3 E_2 E_1$
  - (c)  $E_1 E_2 E_3 E_4$
  - (d)  $E_4^{-1}E_3^{-1}E_2^{-1}E_1^{-1}$

17. (5 points) Let  $A = \begin{pmatrix} 2 & 3 \\ 0 & 1 \end{pmatrix}$ .

(i) State the eigenvalues and eigenspaces of A.

(ii) Draw the eigenspaces of A and label them with the corresponding eigenvalue.



18. (4 points) If A is a matrix with independent columns, explain step by step how to find the QR factorization of A.

19. (3 points) Let m > n. Can n vectors span  $\mathbb{R}^m$ ? Explain your reasoning.

20. (3 points) Let A be an  $m \times n$  matrix. Explain why the matrix  $A^T A$  has non-negative eigenvalues.

# SOLUTION 5

Your initials: \_\_\_\_\_

You do not need to explain your reasoning for questions on this page.

- 1. (6 points) Circle **true** if the statement is true, otherwise, circle **false**.
  - (a) A product of invertible matrices is also invertible.

true false (b) Regardless what A and  $\vec{b}$  are, there is always at least one least-squares solution  $\hat{x}$  to  $A\vec{x} = \vec{b}$ . (true) false (c) If  $A\vec{x}_0 = \vec{b}$ , and  $A\vec{y} = \vec{0}$ , then  $\vec{x} = \vec{x}_0 - 5\vec{y}$  is a solution to  $A\vec{x} = \vec{b}$ . true false (d) An example of a quadratic form is the polynomial  $7x_1^2 + 5x_2^2 - 10x_1x_2 + x_2$ . true (false) (e) If a matrix is invertible then it is also diagonalizable. (false) true (f) A  $n \times n$  matrix A and its echelon form E have the same eigenvalues. false) true 2. (6 points) Circle possible if the set of conditions are create a situation that is possible, otherwise, circle impossible. (a) The columns of matrix A are linearly independent, and  $\text{Null}A^T$  is not trivial. eq A= (:) impossible (possible) (b) A is  $n \times n$ ,  $\lambda \in \mathbb{R}$  is an eigenvalue of A, and dim $(\operatorname{Col}(A - \lambda I)^{\perp}) = 0$ . possible impossible (c) Stochastic matrix P has zero entries and is regular. (possible) impossible (d) A is a square matrix that is not diagonalizable, but  $A^2$  is diagonalizable. impossible  $A = \begin{pmatrix} \circ & \cdot \\ \circ & \bullet \end{pmatrix}$ ,  $A^2 = O_{1\times 1}$ ( possible) (e) A is  $5 \times 4$ ,  $A\vec{x} = \vec{b}$  has three free variables, and dim $(\text{Row}(A)^{\perp}) = 3$ . (possible) impossible (f) A  $m \times n$  matrix A has linear transformation  $T_A$ . The map  $T_A$  can be

possible

 $\begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix}$ 

impossible

one-to-one but not onto.

## You do not need to explain your reasoning for questions on this page.

- 3. (8 points) If possible, give an example of the following. If it is not possible, write "not possible".
  - (a) A matrix that is  $2 \times 4$ , in reduced echelon form, with the dimension of column space being 3, and dimension of null space is 1.

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(b) A  $3 \times 4$  matrix with orthonormal columns.



4. (10 points) A has exactly two distinct eigenvalues, which are -2, and 1.

$$A = \begin{pmatrix} 0 & 1 & -1 \\ 1 & \mathbf{Q} & 1 \\ -1 & 1 & 0 \end{pmatrix}$$

(b) Construct an eigenbasis for eigenvalue 
$$\lambda = 1$$
.  
 $A - (+1)I = \begin{pmatrix} -1 & 1 & -1 \\ 1 & -1 & 1 \\ -1 & 1 & -1 \end{pmatrix} \sim \begin{pmatrix} 1 & -1 & 1 \\ 1 & -1 & 1 \end{pmatrix}$ 
  
 $\Rightarrow \overline{V_2} = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \qquad \overline{V_3} = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$ 
  
 $\overrightarrow{V_3} = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$ 

(c) If possible, construct matrices P and D such that  $A = PDP^{T}$ , and P is a matrix with orthogonal columns, D is diagonal.

.

$$\widehat{\nabla_3} = \overline{V_3} - \frac{V_2 \cdot V_3}{V_2 \cdot V_2} V_2 = \begin{pmatrix} -1 \\ 1 \end{pmatrix} - \frac{-1}{2} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} -1/2 \\ +1/2 \\ 1 \end{pmatrix}, \quad (1) \quad Gram \\ Schmidt$$

can use 
$$\frac{1}{\sqrt{6}} \begin{pmatrix} -1\\ 2 \end{pmatrix}$$
  
=)  $P = \begin{pmatrix} 1/\sqrt{3} & \sqrt{42} & -1/\sqrt{6} \\ -1/\sqrt{3} & \sqrt{42} & 1/\sqrt{6} \\ 1/\sqrt{3} & 0 & 2/\sqrt{6} \end{pmatrix}$  (1) or thogonal matrix  
 $1/\sqrt{3} & 0 & 2/\sqrt{6}$ ) (1) diagonal 3×3  
(1) diagonal 3×3  
(1) diagonal 3×3  
(1) eigens match  
(5) For distance (high school) exams, 5 points on (c) for P=I and D=A.)

5. (10 points) Construct the singular value decomposition of 
$$A = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix}$$
.  
•  $A^{T}A = \begin{pmatrix} 0 & 1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix}$  (1) correct  
• eigenvalues of ATA are, by inspection,  $\lambda = 0, 1, 2$  (1) all correct  
•  $\mathcal{L} = \begin{pmatrix} \sqrt{12} & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} not & \begin{pmatrix} 1 & 0 & 0 \\ 0 & \sqrt{2} & 0 \end{pmatrix}$  and not  $\begin{pmatrix} \sqrt{12} & 0 \\ 0 & 1 \end{pmatrix}$  (2)  $\mathcal{L}$  is 2×3  
•  $\mathcal{L} = \begin{pmatrix} \sqrt{12} & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} not & \begin{pmatrix} 1 & 0 & 0 \\ 0 & \sqrt{2} & 0 \end{pmatrix}$  and not  $\begin{pmatrix} \sqrt{12} & 0 \\ 0 & 1 \end{pmatrix}$  (2)  $\mathcal{L}$  is 2×3  
•  $\mathcal{L} = \begin{pmatrix} \sqrt{12} & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} not & \begin{pmatrix} 0 & \sqrt{2} & 0 \\ 0 & \sqrt{2} & 0 \end{pmatrix} \text{ and not} \begin{pmatrix} \sqrt{12} & 0 \\ 0 & 1 \end{pmatrix}$  (2) elements  
•  $\mathcal{L}$  is a value of the transformed of the transfo

$$\begin{array}{l} \mathcal{U} \quad MATRUX \\ \mathcal{U}_{i} = \frac{1}{\sigma_{i}} A v_{i} = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & 10 \\ 1 & 01 \end{pmatrix} \begin{pmatrix} 1 & 10 \\ 1 & 10 \end{pmatrix} \begin{pmatrix} 1 & 10 \\ 1 & 10 \end{pmatrix} \begin{pmatrix} 1 & 10 \\ 1 & 10 \end{pmatrix} \\ \begin{array}{l} \mathcal{U}_{i} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \\ \begin{array}{l} \mathcal{U}_{i} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \\ \begin{array}{l} \mathcal{U}_{i} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \\ \end{array} \\ \begin{array}{l} \mathcal{U}_{i} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \\ \begin{array}{l} \mathcal{U}_{i} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \\ \end{array} \\ \begin{array}{l} \mathcal{U}_{i} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \\ \end{array} \\ \begin{array}{l} \mathcal{U}_{i} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \\ \end{array} \\ \begin{array}{l} \mathcal{U}_{i} = \begin{pmatrix} 0 \\ 1 \\ 0 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 \\ \begin{array}{l} \mathcal{U}\_{i} = \begin{pmatrix} 0 \\ 0 \\ \end{array} \\ \begin{array}{l} \mathcal{U}\_{i} = \begin{pmatrix} 0 \\ 0

=> A = UEVT, UE, Vas above () this statement necessary.

- 6. (6 points) Circle **true** if the statement is true, otherwise, circle **false**. You do not need to explain your reasoning.
  - (a) For any  $n \times n$  matrix A, and non-zero vectors x and y with Ax = 2x and Ay = 3y, then x and y are orthogonal.



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possible (impossible)

(b) Matrix A has echelon form E, and  $\text{Null}A \neq \text{Null}E$ .

possible impossible

(c) Matrix A has a null space of dimension 1, and the linear transformation  $T_A$  is one to one.

impossible

(d) Matrix A is  $3 \times 4$  and has orthonormal columns.

possible

possible

impossible

if student writes (\$) for H, and (i), (i), (i), (i) for H, 3 ponts You do not need to explain your reasoning for questions on this page. 8. (4 points)  $H = \{ \vec{x} \in \mathbb{R}^4 : x_1 = 5x_4 \}.$ (a) Write down a basis for H. (student can set k to be anything, most will use k=0) (b) Write down a basis for  $H^{\perp}$ .  $\begin{pmatrix} 0\\ 0\\ -5 \end{pmatrix}$   $\begin{pmatrix} 0\\ -5 \end{pmatrix}$   $\begin{pmatrix} 0\\ con also use \begin{pmatrix} -i\\ s \end{pmatrix} \end{pmatrix}$   $\begin{pmatrix} 0\\ correct everything \end{pmatrix}$ 9. (4 points) Fill in the blank (a) Complete the matrix below so that the least squares solution to Ax = bdoes not have a unique solution  $\begin{pmatrix} 1 & \frac{k}{k} \\ 1 & \frac{k}{k} \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 4 \\ 0 \\ 1 \end{pmatrix} \qquad A must have$ linearly dependentcolumns $(b) For the system below, give an example of a choice of vector <math>\vec{b}$  for which the system is inconsistent.  $\begin{pmatrix} 2 & 3 \\ 0 & 0 \\ 4 & 6 \end{pmatrix} \vec{x} = \vec{b} = \begin{pmatrix} \frac{\pi}{1} \\ \frac{\pi}{2} \end{pmatrix} \leftarrow \text{ that element must}$   $\begin{pmatrix} x = \text{ does not metter} \end{pmatrix} \begin{pmatrix} 2 & 3 \\ 0 & 0 \\ 4 & 6 \end{pmatrix} \vec{x} = \vec{b} = \begin{pmatrix} \frac{\pi}{1} \\ \frac{\pi}{2} \end{pmatrix} \leftarrow \text{ that element must}$ (c) The dimension of the subspace of  $\mathbb{R}^4$  spanned by the vectors below is 2.  $\begin{pmatrix} 1\\2\\3\\4 \end{pmatrix}, \quad \begin{pmatrix} 1\\0\\0\\4 \end{pmatrix}, \quad \begin{pmatrix} 0\\-2\\-3\\-3 \end{pmatrix}$ ۱ (d) If  $A = \begin{pmatrix} \vec{a}_1 & \vec{a}_2 \end{pmatrix}$  has QR factorization  $QR = \begin{pmatrix} \vec{q}_1 & \vec{q}_2 \end{pmatrix} \begin{pmatrix} 2 & 4 \\ 0 & 3 \end{pmatrix}$ , the length of  $\vec{a}_2$  is <u>5</u>. 1







12. (4 points) Calculate the least squares solution,  $\hat{x}$ , to the equation below. Don't forget to show your work.

$$\frac{\text{METHOD } 2}{\text{A7A } \hat{x} = \text{A7b}} \qquad () \quad \stackrel{\text{normal}}{\text{equatrms, correct}} \\ \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & -1$$

(2 points) What is the symmetric matrix A associated to the quadratic form

# $x_1^2 - 9x_2^2 - x_3^2 + 16x_1x_3$ $A = \begin{pmatrix} 1 & 0 & 8 \\ 0 & -9 & 0 \\ 8 & 0 & -1 \end{pmatrix}$ (D) main diagonal elements all correct (D) off diag elements all correct

14. (2 points) S is the parallelogram determined by  $\vec{v}_1 = \begin{pmatrix} 2 \\ -2 \end{pmatrix}$ , and  $\vec{v}_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ . If  $A = \begin{pmatrix} 1 & 3 \\ 4 & 2 \end{pmatrix}$ , what is the area of the image of S under the map  $\vec{x} \mapsto A\vec{x}$ ? Justify your reasoning.

asea of 5 under Map = / det A det (20) / = / -10.2 / = 20 or:  $\left( det \left( A \cdot \begin{pmatrix} 2 & 0 \\ -2 & 1 \end{pmatrix} \right) \right) = \left| det \begin{pmatrix} -4 & 3 \\ 4 & 2 \end{pmatrix} \right| = 20$ 

15. (4 points) For what values of  $\vec{b} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$  is the system below consistent? Express your answer using parametric vector form. Justify your reasoning.

$$\begin{pmatrix} 0 & 4 \\ 1 & 3 \\ 2 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 4 & b_1 \\ 1 & 3 & b_2 \\ 2 & 2 & b_3 \end{pmatrix} \sim \begin{pmatrix} 0 & 4 & b_1 \\ 1 & 3 & b_2 \\ 0 & -4 & b_3 - 2b_2 \end{pmatrix} \sim \begin{pmatrix} 4 & 3 & b_2 \\ 0 & 4 & b_1 \\ 0 & 0 & b_3 - 2b_2 + b_1 \end{pmatrix}$$

$$\Rightarrow \quad b_3 - 2b_2 + b_1 = 0$$

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$$\Rightarrow \quad b_1 = \begin{pmatrix} b_1 \\ b_2 \\ b_2 \\ b_3 \end{pmatrix} = b_2 \begin{pmatrix} 2 \\ 0 \\ 0 \\ c_1 \end{pmatrix} + b_3 \begin{pmatrix} -1 \\ 0 \\ c_1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ c_1 \end{pmatrix} + b_2 \begin{pmatrix} 2 \\ 0 \\ c_1 \end{pmatrix} + b_3 \begin{pmatrix} 2 \\ 0 \\ c_1 \end{pmatrix} = b_1 + b_1 + b_2 + b_2 + b_3 + b_2 + b_3 + b_2 + b_3 + b$$

#### Solutions

16) Consider the sequence of row operations that reduce matrix A to the identity.

$$A = \underbrace{\begin{pmatrix} -1 & 2 & 0\\ 1 & 0 & 0\\ 0 & 4 & 1 \end{pmatrix}}_{A} \sim \underbrace{\begin{pmatrix} 1 & 0 & 0\\ -1 & 2 & 0\\ 0 & 4 & 1 \end{pmatrix}}_{E_{1}A} \sim \underbrace{\begin{pmatrix} 1 & 0 & 0\\ 0 & 2 & 0\\ 0 & 4 & 1 \end{pmatrix}}_{E_{2}E_{1}A} \sim \underbrace{\begin{pmatrix} 1 & 0 & 0\\ 0 & 2 & 0\\ 0 & 0 & 1 \end{pmatrix}}_{E_{3}E_{2}E_{1}A} \sim \underbrace{\begin{pmatrix} 1 & 0 & 0\\ 0 & 1 & 0\\ 0 & 0 & 1 \end{pmatrix}}_{E_{4}E_{3}E_{2}E_{1}A} = I_{3}$$

(i) Construct the four elementary matrices  $E_1$ ,  $E_2$ ,  $E_3$ , and  $E_4$ .

$$E_1 = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}, E_2 = \begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, E_3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0.5 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

- (ii) Consider the matrix products listed below. Which (if any) represents A, and which (if any) represents  $A^{-1}$ ?
  - i.  $E_1^{-1}E_2^{-1}E_3^{-1}E_4^{-1}$ ii.  $E_4E_3E_2E_1$ iii.  $E_1E_2E_3E_4$ iv.  $E_4^{-1}E_3^{-1}E_2^{-1}E_1^{-1}$

$$A = E_1^{-1} E_2^{-1} E_3^{-1} E_4^{-1}, \text{ and } A^{-1} = E_4 E_3 E_2 E_1.$$
17) Let  $A = \begin{pmatrix} 2 & 3 \\ 0 & 1 \end{pmatrix}.$ 

(i) State the eigenvalues and eigenspaces of A.  $\lambda_1 = 2, \lambda_2 = 1$  $\lambda_1$ -eigenspace is Span $\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix} \}, \lambda_2$ -eigenspace is Span $\{ \begin{pmatrix} 3 \\ -1 \end{pmatrix} \}$ 

(ii) Draw the eigenspaces of A and label them with the corresponding eigenvalue.



- 18) To create Q, Gram-Schmidt vectors, normalize each vector so they all have unit length, place vectors into matrix. To create R, compute  $R = Q^T A$ .
- 19) Place vectors into a matrix. The matrix will be  $m \times n$ . Because n < m, the matrix has at most n pivots. The dimension of the column space of the matrix is at most n, which means the vectors cannot span  $\mathbb{R}^m$ .
- 20) Let  $v_j$  be an eigenvector of **A^TA**

$$||Av_j|| = Av_j \cdot Av_j = v_j^T A^T Av_j = \lambda_j v_j \cdot v_j = \lambda_j ||v_j||^2$$

Therefore all eigenvalues are positive or zero, but never negative.